Point Group Assignments and Character Tables



W. H. Eeman

A Simpler Approach



Inorganic Chemistry Chapter 1: Table 6.2 Table 6.2 The composition of some common groups

W. H. Freeman



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LINEAR MOLECULES

Do in fact fit into scheme - but they have an infinite number of symmetry operations.

Molecular axis is C_{∞} - rotation by any arbitrary angle $(360/\infty)^{\circ}$, so infinite number of rotations. Also any plane containing axis is symmetry plane, so infinite number of planes of symmetry.

Divide linear molecules into two groups:

(i) No centre of symmetry, e.g.: $H \longrightarrow C \longrightarrow N$ C_{∞}

No C₂'s perp. to main axis, but $\infty \sigma_v$'s containing main axis: point group $C_{\infty v}$





Point group $D_{\infty h}$

Highly symmetrical molecules

A few geometries have several, equivalent, highest order axes. Two geometries most important:

POINT GROUPS

A collection of symmetry operations all of which pass through a single point

A point group for a molecule is a quantitative measure of the symmetry of that molecule

ASSIGNMENT OF MOLECULES TO POINT GROUPS

STEP 1 : LOOK FOR AN AXIS OF SYMMETRY

If one is found - go to STEP 2

If not: look for

(a) plane of symmetry - if one is found, molecule belongs to point group C_s

Regular tetrahedron





 $3C_4$'s (along F-S-F axes) also $4C_3$'s. $6C_2$'s, several planes, S_4 , S_6 axes, and a centre of symmetry (at S atom) Point group O_h

These molecules can be identified without going through the usual steps.

Note: many of the more symmetrical molecules possess many more symmetry operations than are needed to assign the point group.



So, What IS a group?





And, What is a Character???



A GROUP is a collection of entities or elements which satisfy the following four conditions:

1) The product of any two elements (including the square of each element) must be an element of the group. For symmetry operations, the multiplication rule is to successively perform operations.

2) One element in the group must commute with all others and leave them unchanged. Therefore the "E",

$$EX = XE = X$$

3) The associative law of multiplication must hold

$$A(BC) = (AB)C$$

4) Every element must have a reciprocal which is also an element of the group. i.e.,

$$X(X^{-1}) = (X^{-1}) X = E$$

Note: An element may be its own reciprocal.

Groups may be composed of anything: symmetry operations, nuclear particles, etc. Simplest is +1, -1.



W. Н.

Table 6.3 The components of a character table

Name of point group*	Symmetry operations <i>R</i> arranged by class (<i>E</i> , <i>C_n</i> , etc.)	Functions	Further functions	Order of group, <i>h</i>
Symmetry species (Γ)	Characters (χ)	Translations and components of dipole moments (<i>x</i> , <i>y</i> , <i>z</i>), of relevance to IR activity; rotations	Quadratic functions such as <i>z</i> ² , <i>xy</i> , etc., of relevance to Raman activity	

* Schoenflies symbol.

W. H.

4. The C_{nv} Groups

Czu	E	$C_2 = \sigma_v($	$(xz) \sigma'_v(yz)$	1		
$ \frac{A_1}{A_2} $ $ \frac{B_1}{B_2} $	1 1 1		$\begin{array}{c}1\\1\\-1\\-1\\1\\1\end{array}$	z Rz x, Ry y, Rz	x ² , y ² , z ² xy xz yz	
C 3 v	E	2 <i>C</i> ₃	σ_v			
A 1 A 2 E	1 1 2	1 1 	$ \begin{array}{c c} 1 & z \\ -1 & R_z \\ 0 & (x, y)(z) \end{array} $	(R_x, R_y)	$x^2 + y^2, z$ $(x^2 - y^2, z)$	2 xy)(xz, yz)
C_{4v}	E	2 <i>C</i> 4 <i>C</i> 2	20° 20°		1	
$ \begin{array}{c} A_1 \\ A_2 \\ B_1 \\ B_2 \\ E \end{array} $	1 1 1 1 2	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$z R_z$ $(x, y)(R_z)$	$\begin{array}{c} x^2 \\ x^2 \\ xy \\ xy \\ (xz \end{array}$	$+ y^2, z^2$ $- y^2$
Cs.	E	2 <i>C</i> ₅	2 <i>C</i> ₅²	50,		1
$ \begin{array}{c} A_1 \\ A_2 \\ E_1 \\ E_2 \end{array} $	1 1 2 2	1 1 2 cos 72° 2 cos 144°	1 1 2 cos 144° 2 cos 72°		z R _x (x, y)(R _x , R	$x^{2} + y^{2}, z^{2}$ (xz, yz) (x ² - y ² , xy)
C60	E	2C ₆ 2C ₃	$C_2 3\sigma_v$	3σ ₄		
$ \begin{array}{c} A_1 \\ A_2 \\ B_1 \\ B_2 \end{array} $	1 1 1	1 . 1 1 . 1 	$ \begin{array}{cccc} 1 & 1 \\ 1 & -1 \\ -1 & 1 \\ -1 & -1 \end{array} $	$ \begin{array}{c c} 1 & z \\ -1 & R_z \\ -1 & 1 \\ 1 \end{array} $		$x^2 + y^2, z^2$
E_1 E_2	2 2	$ \begin{array}{ccc} 1 & -1 \\ -1 & -1 \end{array} $	$ \begin{array}{ccc} -2 & 0 \\ 2 & 0 \end{array} $	0 (x, 0	, y)(R _x , R ₇)	(xz, yz) $(x^2 - y^2, xy)$

4. The C_{nv} Groups

Czu	E	$C_2 = \sigma_v($	$(xz) \sigma'_v(yz)$	1		
$ \frac{A_1}{A_2} $ $ \frac{B_1}{B_2} $	1 1 1		$\begin{array}{c}1\\1\\-1\\-1\\1\\1\end{array}$	z Rz x, Ry y, Rz	x ² , y ² , z ² xy xz yz	
C 3 v	E	2 <i>C</i> ₃	σ_v			
A 1 A 2 E	1 1 2	1 1 	$ \begin{array}{c c} 1 & z \\ -1 & R_z \\ 0 & (x, y)(z) \end{array} $	(R_x, R_y)	$x^2 + y^2, z$ $(x^2 - y^2, z)$	2 xy)(xz, yz)
C_{4v}	E	2 <i>C</i> 4 <i>C</i> 2	20° 20°		1	
$ \begin{array}{c} A_1 \\ A_2 \\ B_1 \\ B_2 \\ E \end{array} $	1 1 1 1 2	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$z R_z$ $(x, y)(R_z)$	$\begin{array}{c} x^2 \\ x^2 \\ xy \\ xy \\ (xz \end{array}$	$+ y^2, z^2$ $- y^2$
Cs.	E	2 <i>C</i> ₅	2 <i>C</i> ₅²	50,		1
$ \begin{array}{c} A_1 \\ A_2 \\ E_1 \\ E_2 \end{array} $	1 1 2 2	1 1 2 cos 72° 2 cos 144°	1 1 2 cos 144° 2 cos 72°		z R _x (x, y)(R _x , R	$x^{2} + y^{2}, z^{2}$ (xz, yz) (x ² - y ² , xy)
C60	E	2C ₆ 2C ₃	$C_2 3\sigma_v$	3σ ₄		
$ \begin{array}{c} A_1 \\ A_2 \\ B_1 \\ B_2 \end{array} $	1 1 1	1 . 1 1 . 1 	$ \begin{array}{cccc} 1 & 1 \\ 1 & -1 \\ -1 & 1 \\ -1 & -1 \end{array} $	$ \begin{array}{c c} 1 & z \\ -1 & R_z \\ -1 & 1 \\ 1 \end{array} $		$x^2 + y^2, z^2$
E_1 E_2	2 2	$ \begin{array}{ccc} 1 & -1 \\ -1 & -1 \end{array} $	$ \begin{array}{ccc} -2 & 0 \\ 2 & 0 \end{array} $	0 (x, 0	, y)(R _x , R ₇)	(xz, yz) $(x^2 - y^2, xy)$

6. The D_{nh} Groups

D 2 k	E	$C_2(z)$	C2(y)	$C_2(x)$	i	σ(xy)	$\sigma(xz)$	σ(yz)			
Ae Ble B2e B3e Au B1u B2u B3u	1 1 1 1 1 1 1		-1 -1 -1 -1 -1 -1		1 1 1 -1 -1 -1				R ₁ R _y R _x z y x	x ² , xy xz yz	y ² , z ²
D3M	E	$2C_{3}$	3C ₂ σ _h	2.53	300	1		-			
A ₁ ', A ₂ ' E' A ₁ " A ₂ " E"	1 1 2 1 1 2		$ \begin{array}{c} 1 \\ -1 \\ 0 \\ -1 \\ -1 \\ 0 \\ -2 \end{array} $	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		R _z (x,) z (R _x	v) , R _y)	$x^2 + y$ $(x^2 - z)$ (xz, yz)	² , z ² v ² , xy)		
DAN	E	2 <i>C</i> ₄	C ₂ 2C ₂	′ 2 <i>C</i> ₂″	i	254	σ _R 2σ	· 2σ.		I	
A 1.9 A 2.9 B 1.0 B 2.0 E 0 A 1.1 A 2.1 B 2.1 E 0 E 0 C	1 1 1 2 1 1 1 2	$ \begin{array}{c} 1 \\ -1 \\ -1 \\ 0 \\ 1 \\ -1 \\ -1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0$	1 - 1 1	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c} 1 \\ 1 \\ 2 \\ -1 \\ -1 \\ -1 \\ -2 \\ -2 \\ \end{array} $	i 1 1 1 1 1 1 1 1 1 	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	R _z (R _x , z (x, y	R _y)	$ x^{2} + y^{2}, z^{2} x^{2} - y^{2} xy (xz, yz) $

5. The D_{nh} Groups

D2h	E	$C_2(z)$	C2())	$C_1(x)$	1	$\sigma(xy)$	$\sigma(xz)$	o(yz)			
A. B1. B2. B3. A. B1. B1. B2. B3. B3.				1 -1 -1 1 -1 -1 1 1			-1 -1 -1 -1 -1	-1 -1 -1 -1 -1 -1 -1	R. R, R, z y x	x ² , xy xz yz	y ² , z ²
Dam	E	2C,	3C ₂ σ ₁	2.53	$3\sigma_v$	1	1				
A 1 2 A	1 2 1 1 2	1 1 1 1		$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$-1 \\ -1 \\ -1 \\ 1 \\ 0$	R: (x,) 	v) . R,)	$x^2 + y$ $(x^2 - y)$ (xz, yz)	² , z ² v ² , xy)		
DAR	E	2 <i>C</i> ₄	C ₂ 2C,	2C2*	1	25. 0	7 ₈ 2σ	. 201			
A 1. A 1. B 2. B 2. A 2. B 2. B 2. A 2. B 2.	1 1 1 2 1 1 1 1 2		$\begin{bmatrix} 1 & -1 \\ 1 & -2 \\ -2 & -1 \\ 1 & -1 \\ 1 & -2 \\ -2 & -2 \end{bmatrix}$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	1 1 2 -1 -1 -1 -1 -2		$\begin{array}{c} 1 \\ 1 \\ -2 \\ -1 \\ -1 \\ -1 \\ -1 \\ -1 \\ 2 \end{array}$	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	R. (R z (x. y	R,)	$x^{2} + y^{2}, z^{2}$ $x^{2} - y^{2}$ xy (xz, yz)

9. The Cubic Groups (Continued).

T.	E	4C3	$4C_{3}^{2}$	3C,	i	4 <i>S</i> 6	4 <i>S</i> 6 ⁵	3on				$\varepsilon = \exp(2i)$	πi/3)
A _g	1	1	1	1	ļ	1	1	1				$x^2 + y^2 +$	<u>z²</u> -
E,		с с* с	ε* ε ε*	1	-1 1 1 -1	-1 ε ε* -ε	-1 c* c*	-1 1) 1)				$\begin{array}{c} (2z^2 - x^2 - x^2$	$-y^2$,
Eu To Tu	1 3 3	ε* 0 0	е 0 0	 - 	$-\frac{1}{3}$	e+ 0 0	$-\varepsilon$ 0	-1 -1	(<i>k</i>	R_x, R_y	, <i>R</i> _z)	(xz, yz, xy))
T	E	8C:	3C2	6S4	6 0 6		-	•	(,	., ,, ,, -,			
A1	1	1	1	1	ļ				x ²	+ y ² -	+ z ²	-	
E A 2	2		2	2 0	-1 0				(2z	$x^{2} - x^{2}$	² _ y ²	•	
T_1	3		-1	I	-1	(R	x, Ry,	<i>R</i> _z)	x *	y*)			
0	<i>E</i>	6 <i>C</i> .	$3C_2$	$(=C_4)$	¹ 2) $8C_{3}$	$\begin{array}{c} 1 & (x, \\ 0 & 6C \end{array}$	y, z) - 2	•	((xy	', xz, j	' z)		
A1	1	1		1		l	1					$\frac{1}{x^2+y^2+z}$	2
A ₂ E	1 2	-1 0	l	1 2	-1 -1		1 0					$(2z^2 - x^2 - x^2)$	y ² ,
$\begin{bmatrix} T_1 \\ T_2 \end{bmatrix}$	3	1 -1		-1 -1) - () —	1	(R _x , F	(r, R_z)	; (x,)	, z)	~)) (YV Y7 V7)	
0,	E	8C3	6C2	6C4	3C2(=	= C ₄ ²)	i	6S4	8 <i>5</i> 6	3 a ,	6 0 4		
A 19 A 29 E9	1 1 2	1 1 -1	1 -1 0	1 -1 0		1 1 2	1 1 2	1 1 0	1 1 -1	1 1 2	1 -1 0		$\frac{x^2 + y^2 + z^2}{(2z^2 - x^2 - y^2)}$
T_{1q} T_{2q}	3 3 1	0 0 1	-1 1			1	3	1 -1	0	-1 -1	-1	(R_x, R_y, R_z)	(xz, yz, xy)
$\begin{array}{c} \mathcal{A}_{2w} \\ \mathcal{A}_{2w} \\ \mathcal{E}_{w} \\ \mathcal{T}_{1w} \\ \mathcal{T}_{2w} \end{array}$	1 2 3 3	1 -1 0 0	-1 -1 1	-1 0 1 -1	_	1 2 1 1	-1 -2 -3 -3	-1 0 -1	-1 -1 0 0	-1 -2 1 1	1 0 1 -1	(x, y, z)	



Table 6.5 The C_{3v} character table



W. H.

Inorganic Chemistry Chapter 1: Figure 6.13



W. H. EEMAN

Consequences of Symmetry

- Only the molecules which belong to the **Cn**, **Cnv**, or **Cs** group can have a permanent dipole moment.
- A molecule may be chiral only if it does not have an axis of improper rotation **Sn**.
- IR Allowed transitions may be predicted by symmetry operations
- Orbital overlap may be predicted and described by symmetry

Character table for $C_{\scriptscriptstyle \! \infty \nu}$ point group

	E	2C _∞	•••	∞ σ _v	linear, rotations	quadratic
Α ₁ =Σ+	1	1		1	Z	x ² +y ² , z ²
A ₂ =Σ ⁻	1	1		-1	R _z	
Е ₁ =П	2	2cos(Φ)		0	(x, y) (R _x , R _y)	(xz, yz)
E ₂ =Δ	2	2cos(2φ)		0		(x ² -y ² , xy)
Е ₃ =Ф	2	2cos(3φ)		0		
•••						

Character table for $D_{{\scriptscriptstyle \infty}{\scriptscriptstyle h}}$ point group

	E	2C _∞	 ∞o ^v	.1	2S _∞	 ∞C'₂	linear functions, rotations	quadratic
Α _{1g} =Σ ⁺ _g	1	1	 1	1	1	 1		x ² +y ² , z ²
A _{2g} =Σ⁻ _g	1	1	 -1	1	1	 -1	R _z	
Е _{1g} =П _g	2	2cos(φ)	 0	2	-2cos(φ)	 0	(R _x , R _y)	(xz, yz)
E _{2g} =Δ _g	2	2cos(2φ)	 0	2	2cos(2φ)	 0		(x²-y², xy)
E₃g=Φg	2	2cos(3φ)	 0	2	-2cos(3φ)	 0		
•••			 •••			 		
Α _{1u} =Σ+ _u	1	1	 1	-1	-1	 -1	Z	
A _{2u} =Σ⁻ _u	1	1	 -1	-1	-1	 1		
Е _{1u} =П _u	2	2cos(φ)	 0	-2	2cos(φ)	 0	(x, y)	
E _{2u} =Δ _u	2	2cos(2ф)	 0	-2	-2cos(2φ)	 0		
Е _{зи} =Ф _и	2	2cos(3φ)	 0	-2	2cos(3φ)	 0		
••••			 			 		